

# PCB Assembly

The  $\mu$ Car consists of 2 PCBs. Download the [Eagle files](#).

- [Vehicle Main Board](#)
- [Odometer Board](#)

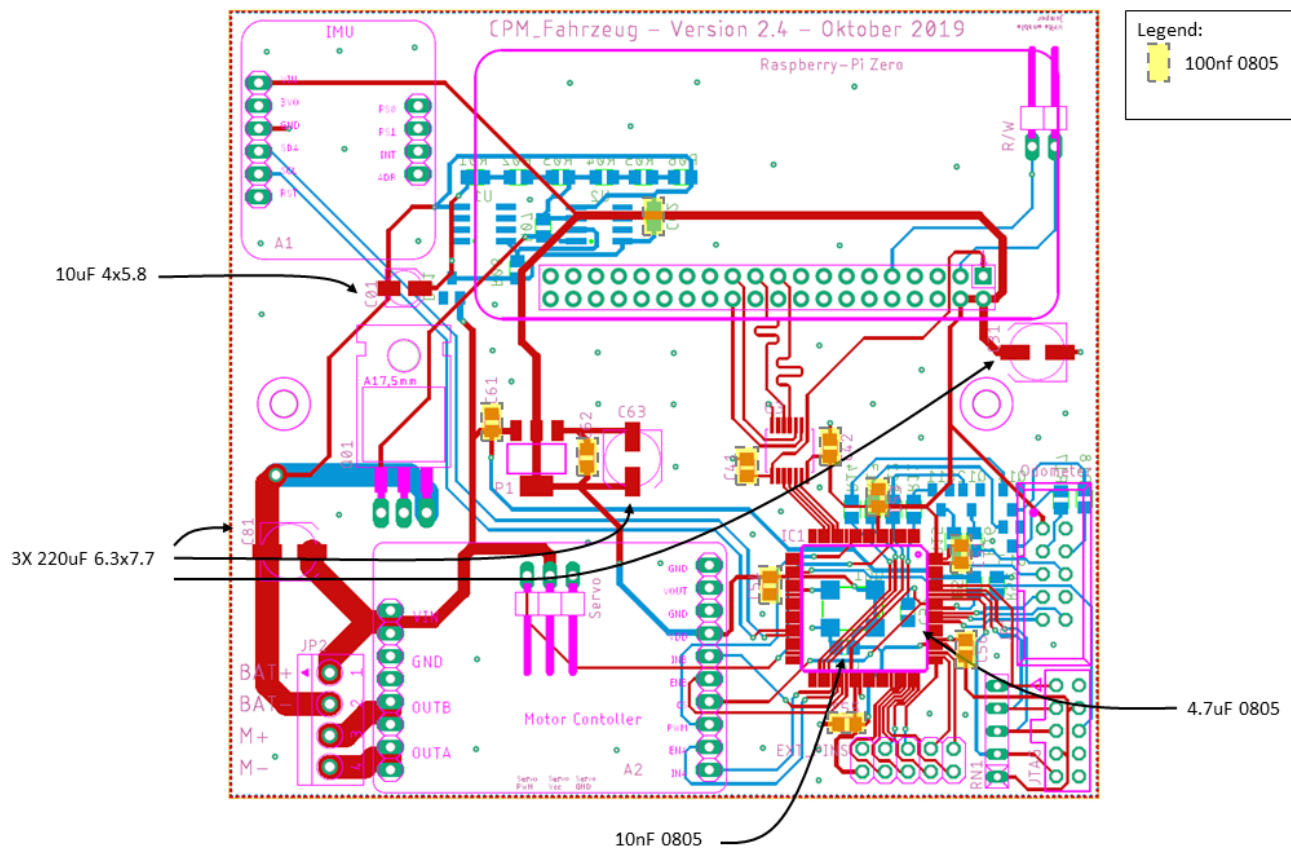
For questions please contact Patrick Scheffe.

## Vehicle Main Board

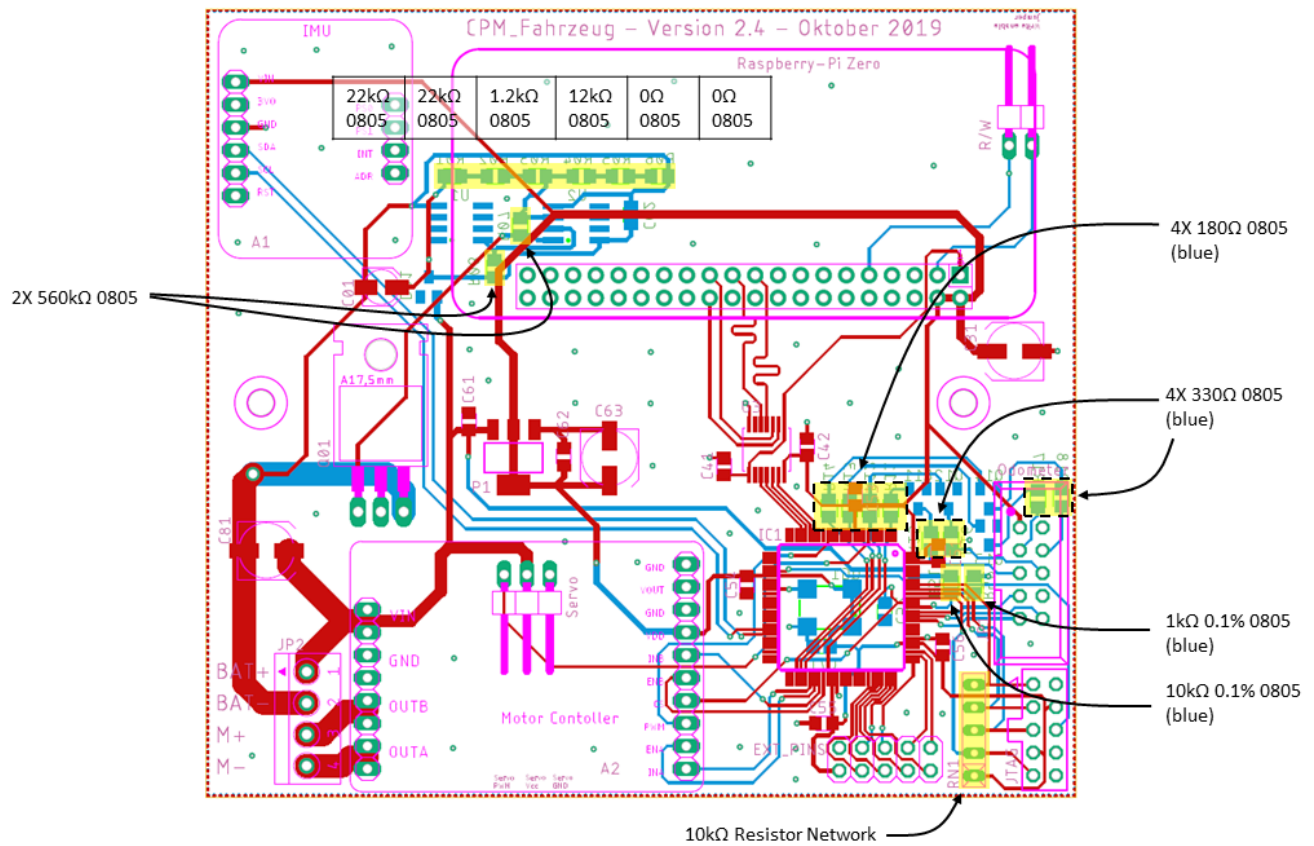
The main board contains most electrical components necessary for controlling the vehicle:

- Raspberry Pi Zero W ([Mid Level Controller](#))
- ATmega2560 ([Low Level Controller](#))
- IMU BNO055
- Motor Controller VN15019

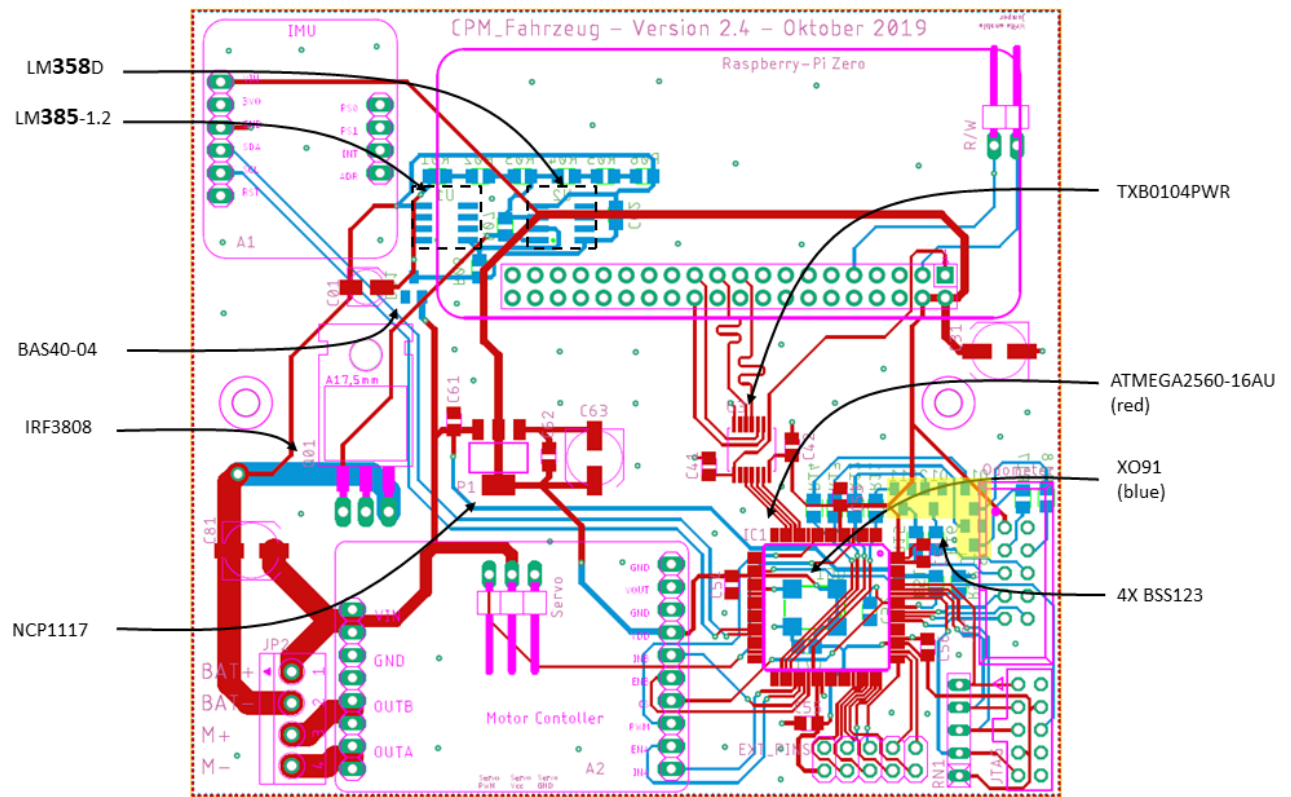
### 1. Component Placement: Capacitors



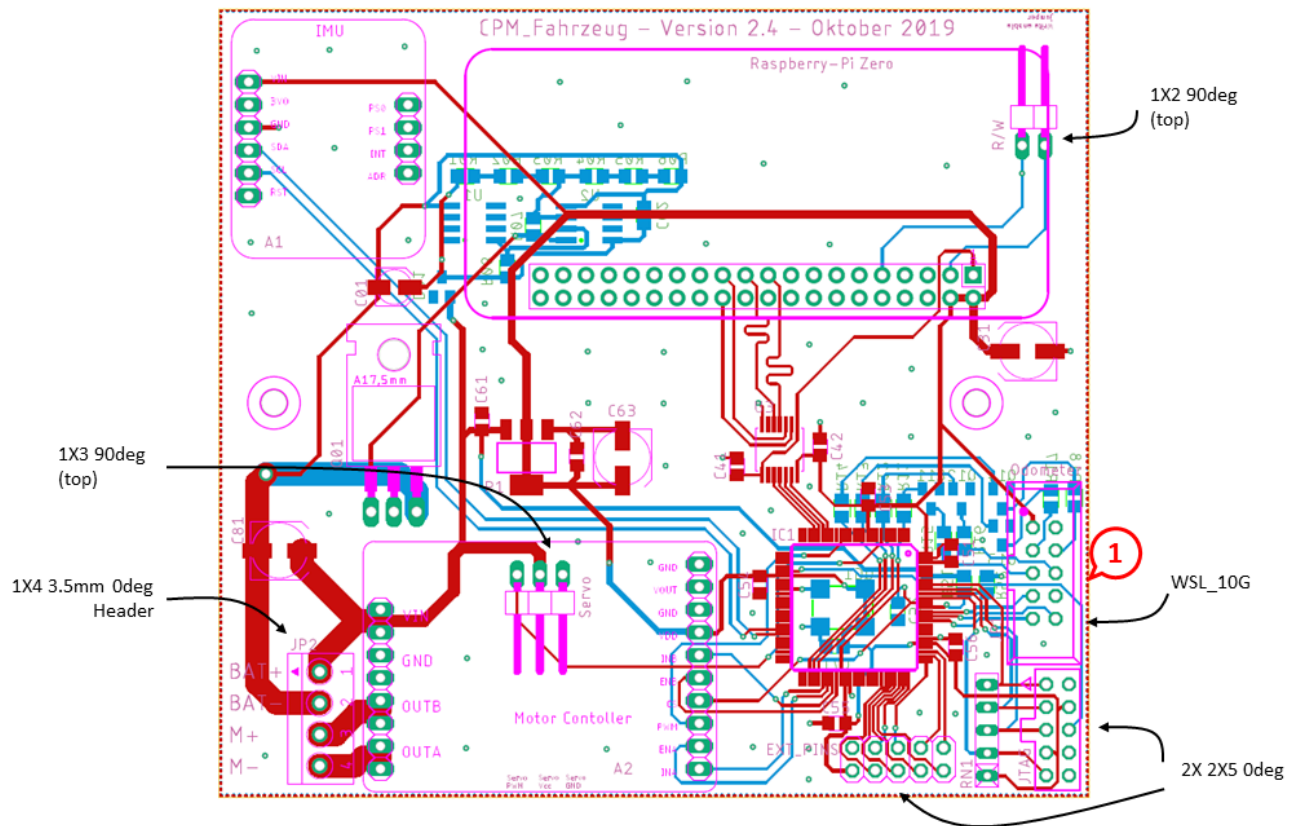
## 1. Component Placement: Resistors



# 1. Component Placement: ICs



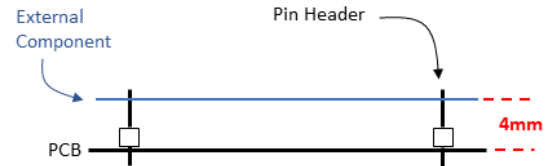
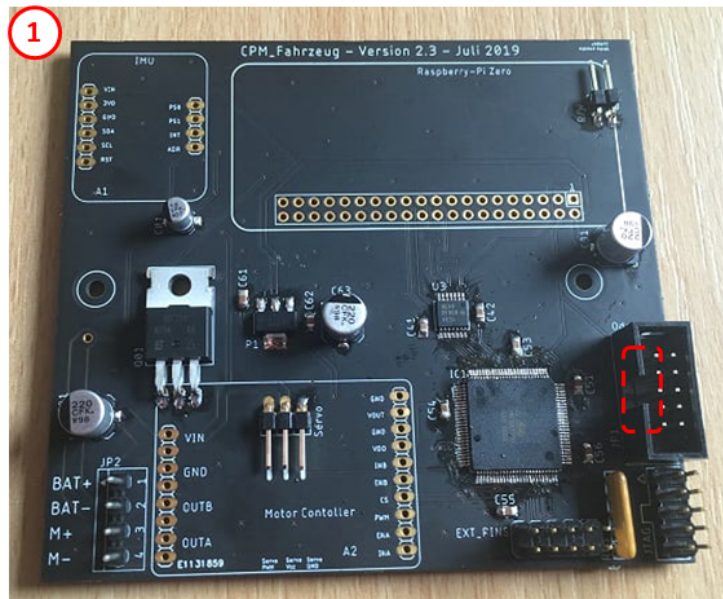
## 1. Component Placement: Connectors



2



## 2. Notes

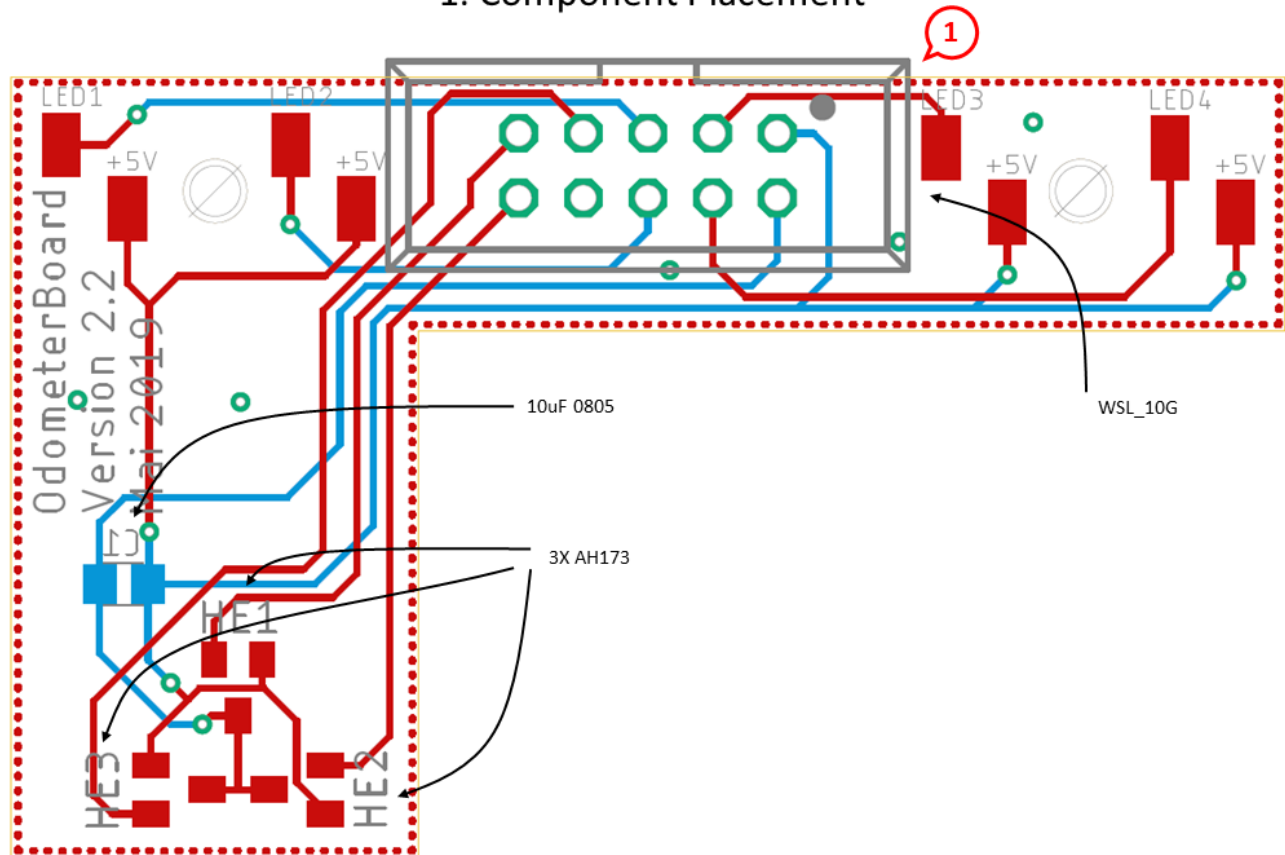


Note	Instructions
1	Take note of orientation Tab (form fit) points inward
2	Use spacers to ensure <b>4mm</b> gap between external components and PCB Applies to IMU (A1), Motor Controller (A2) and Raspberry Pi

## Odometer Board

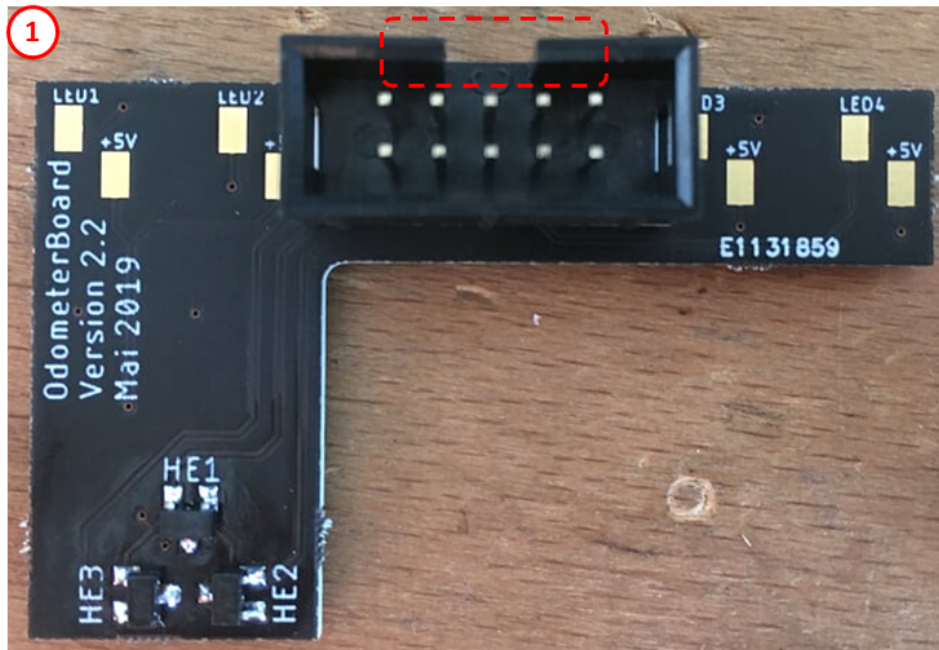
The odometer board contains two important parts. Firstly, the hall sensors are placed on it and are measuring changes of the magnetic field. These changes result from the rotation of the magnet, which is placed on top of the motor shaft. That allows measuring the driven distance and the velocity. Secondly, the board provides the connections to the LEDs which are necessary for the [IPS](#).

## 1. Component Placement





## 2. Notes



Note	Instructions
1	Take note of orientation Tab (form fit) at top